

7	Digital Control Strategies
7.1	Introduction
7.2	Canonical Form for Digital Controllers
7.3	Pole Placement
7.3.1	Regulation
7.3.2	Tracking
7.3.3	Some Properties of the Pole Placement
7.3.4	Some Particular Pole Choices
7.4	Tracking and Regulation with Independent Objectives
7.4.1	Polynomial Design
7.4.2	Time Domain Design
7.5	Tracking and Regulation with Weighted Input
7.6	Minimum Variance Tracking and Regulation
7.6.1	Design of Minimum Variance Control
7.6.2	Generalized Minimum Variance Control
7.7	Generalized Predictive Control
7.8	Linear Quadratic Control
7.9	Concluding Remarks
7.10	Problems